URBANFYE

An Outdoor Localization System for Public Transport

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PROBLEMS OF PUBLIC TRANSPORT IN DEVELOPING COUNTRIES





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No Information Boards

OBJECTIVE

- An application which runs on a commuter's mobile phone is a feasible solution
- The app should give the following
 - Current location of the commuter
 - Time that the bus would take to reach the destination

A G.P.S BASED SOLUTION

 Empower the user with a GPS based mobile application which she can use anytime

But!!



Energy Consumed by GPS

WHAT CAN BE DONE?

Use of **mobile sensors** to localize vehicles without using GPS

Landmarks: Specific anomalies on the route which can be detected using the mobile sensors







COLLECT SENSOR DATA



DATABASE AND TRAVERSAL GRAPH



DETECT LANDMARK USING SENSORS



LOCALIZE





ARE VIRTUAL LANDMARKS FEASIBLE?





Latitude

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• Only stray hotspots detected



• Unplanned placement of cell towers.



Physical



WHAT ABOUT THE PHYSICAL ONES?









AN ISSUE WITH PHYSICAL LANDMARKS

Volatile Landmarks

May or may not occur on a route.



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Bus skips a designated bus-stop





HANDLING VOLATILE LANDMARKS

Confidence of Landmarks: Probability of a bus encountering a landmark given that it has already encountered the previous landmark



WE THUS PRESENT - URBANEYE

Builds Landmark Database





NAVIGATION: LOCALIZATION



NAVIGATION: TRAVEL TIME ESTIMATION



Assuming there are a total of n landmarks between the source and destination and m landmarks have already passed,

$$ETA = \sum_{i=m}^{n-1} p_{ji} * g_{ji}$$

where *j* is the landmark from which *i* was reached

In this example, n = 6 and m = 3

Hence we have,

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ETA = (15*0.4) + (6*0.6) + 10*0.6 = 15.6



SYSTEM ARCHITECTURE







IST (UTC+5:30)

Time zone

💶 India

Country

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20

89'30' @ 2011 Maph

Country

India

WAR DRIVING



- We collected sensor trails for up and down trips (**60 trails**) over a month's duration.
- Total coverage of the routes was around **75kms**
- Different types of devices were used, for e.g. Google Nexus4, Micromax A092, Samsung Galaxy Tab 3



EVALUATION : DETECTION OF LANDMARKS

Detection Accuracy for a route in Durgapur

| Landmark | Actual | Detected (%) | False Positive (%) | FPE* (%) |
|------------------|--------|-----------------|--------------------------|-----------------|
| Turn | 32 | 31 (96.8) | 10 (31.2) | 0 (0) |
| Speed Breaker | 9 | 8 (87.5) | 3 (37.5) | 0 (0) |
| Bus Stops | 42 | 34 (80.9) | 13 (38.2) | 2 (4.76) |

• Bus Stops have comparatively low detection because of volatility

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• Applying PTA guard intervals reduces the false positive cases considerably





*FPE: False positives after elimination by PTA guard intervals

EVALUATION : DETECTION OF LANDMARKS

Accuracy metrics for the 3 cities

| City | Turns | | | Speed Breakers | | | Bus Stops | | |
|-----------|-------|------|------|----------------|------|------|-----------|------|------|
| | Р | R | A | Р | R | A | Р | R | A |
| Durgapur | 1 | 0.94 | 0.94 | 1 | 1 | 1 | 0.93 | 0.83 | 0.78 |
| Kharagpur | 1 | 1 | 1 | 1 | 0.94 | 0.94 | 0.88 | 0.88 | 0.78 |
| Kolkata | 1 | 0.97 | 0.97 | 1 | 0.89 | 0.89 | 0.94 | 0.81 | 0.77 |

- Almost close to 1 values for Precision, Recall and Accuracy for turns and speed breakers
- Bus stops again have comparatively low values because of volatility





NAVIGATION EVALUATION

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- We compare localization accuracy w.r.t **Dejavu**.
- We compared the travel time estimates with that of Google maps.
- Energy consumption comparisons were done against Dejavu and GPS.

Aly, Heba, and Moustafa Youssef. "Dejavu: an accurate energy-efficient outdoor localization system." *Proceedings of the 21st ACM SIGSPATIAL International Conference on Advances in Geographic Information Systems*. ACM, 2013.



COMPETING HEURISTIC

Dejavu (Alexandria, Egypt)









EVALUATION: LOCALIZATION ACCURACY



- Dejavu performs very bad for low density landmarks routes
- The average localization error is 50m

Localization Error over a route



EVALUATION : TRAVEL TIME ESTIMATE



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- Simulated the bus route for Google Maps
- Google maps doesn't consider wait time at bus stops
- Hence, UrbanEye gives better estimate than Google Maps

Error Percentage is given as;

 $\frac{\text{abs (Actual Time - Estimated Time)}}{\text{Actual Time}} \times 100$



ON-SERVER AND OFF-SERVER URBANEYE

We developed two versions of the application

- On-server : Navigation is carried on server and sensor data is offloaded
- Off-server : Navigation is performed on the device
- We hence evaluate how much overhead does offloading sensor data have over energy consumption

EVALUATION : ENERGY CONSUMPTION



- UrbanEye consumes 50% less energy compared to GPS
- The on-server version consumes same energy as Dejavu
- The off-server version
 consumes 86% less energy
 than GPS



CONCLUSION

- This is the first work which gives proper data structure and framework for localization under uncertainty
- The **PTA** efficiently utilizes the in uncertainty
- Compared to a deployed system Google Maps and research system Dejavu, UrbanEye fairs quite well

ACKNOWLEDGEMENT

- Special Thanks to
 - Information Technology Research Academy, India
 - Xerox Research Centre India
 - ACM India IARCS



THANK YOU!

UrbanEye: http://www.cnergres.iitkgp.ac.in/urbaneye/

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